

Light load servo drive-control integrated robot

Features

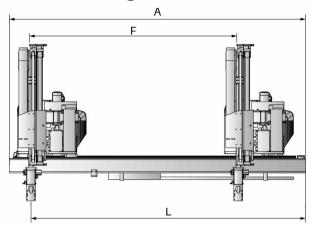
- Advanced driver ensures stable performance;
- Highly modular design and card splice structure makes it only has to change corresponding module without disassembling
 and replacing the whole system during maintenance, which is better than most of other drive-control units in the market.
- The shared DC bus makes the driver work more stably, with better overload capacity. Moreover, it only needs a regenerative resistor, which saves mount space.
- The main control module and the servo module are connected in the unified base plate, which avoid cumbersome manual wiring and increases the system's stability and reliability;
- The servo parameters can be set by the controller directly;
- The bus controlled interface is suitable for all kinds of IMMs (China GB, European and Japanese standards), suitable for new 7" manipulator;
- It has similar stability like drive-control splite system, but also saves the labor works of wiring, and it shortens the size of the control box.

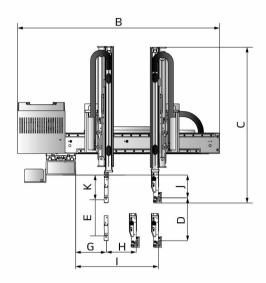
Application

This robot series is designed for rapid and precise removal of products from injection molding machine, and place them at desired locations. Apply to 2/3-plate mold or hot runner system. Capable of arranging, stacking, quality checking and insert molding. Suitable for injection molding machine with clamping force 80~300 tons.



Outline Drawings





Specifications

| Model | | ST3- 850-1400T-S2-I-Lite | ST3- 1100-1600T-S2-I-Lite | ST5- 850-1400DT-S2-I-Lite | ST5- 1100-1600DT-S2-I-Lite |
|-----------------------------------|----------|-----------------------------|------------------------------|------------------------------|-------------------------------|
| Robot type | | Single kick stroke beam | Single kick stroke beam | Single kick stroke beam | Single kick stroke beam |
| IMM (ton) | | 80-200 | 250-300 | 80-200 | 250-300 |
| Traverse Stroke (mm) | | 1400 | 1600 | 1400 | 1600 |
| Crosswise Stroke (mm) | Main Arm | 700 | 950 | 550 | 850 |
| | Sub Arm | ÷ | æ | 550 | 850 |
| Vertical stroke (mm) | Main Arm | 850 | 1100 | 850 | 1100 |
| | Sub Arm | <u>u</u> | ë | 850 | 1100 |
| Max Load (with tool) (kg) | | 3 | 5 | 3 | 5 |
| Min Pick-out Time (sec) | | 1.4 | 1.6 | 1.4 | 1.6 |
| Min Cycle Time (sec) | | 5.9 | 6.5 | 5.9 | 6.5 |
| Air Pressure (bar) | | 4~6 | 4~6 | 4~6 | 4~6 |
| Max. Air Consumption (NI/cycle) * | | 4 | 4 | 4 | 4 |
| Weight (kg) | | 230 | 260 | 260 | 290 |
| Dimensions (mm) | А | 2060 | 2220 | 2060 | 2220 |
| | В | 1350 | 1600 | 1350 | 1600 |
| | С | 1200 | 1250 | 1200 | 1250 |
| | D | 850 | 1100 | 850 | 1100 |
| | Е | - | - | 850 | 1100 |
| | F | 1400 | 1600 | 1400 | 1600 |
| | G | | . c | 140 | 90 |
| | Н | | - | 155 | 150 |
| | 1 | 780 | 1050 | 780 | 1050 |
| | J | 200 | 230 | 200 | 230 |
| | К | ÷ | e | 210 | 250 |
| | L | 1800 | 2100 | 1800 | 2100 |

Notes: 1) "M"stands for middle mold detector. (suitable for three-plate mold.)

[&]quot;EM12" stands for EUROMAP 12 communication interface.

[&]quot;EM67" stands for EUROMAP 12 communication interface.

[&]quot;N" stands for non-operation side, operation side without "N" $\,$

²⁾ Power supply: 1Φ, 200~240V, 50/60Hz.

^{3) &}quot; * " Max. air consumption for vacuum device 60Nl/min.